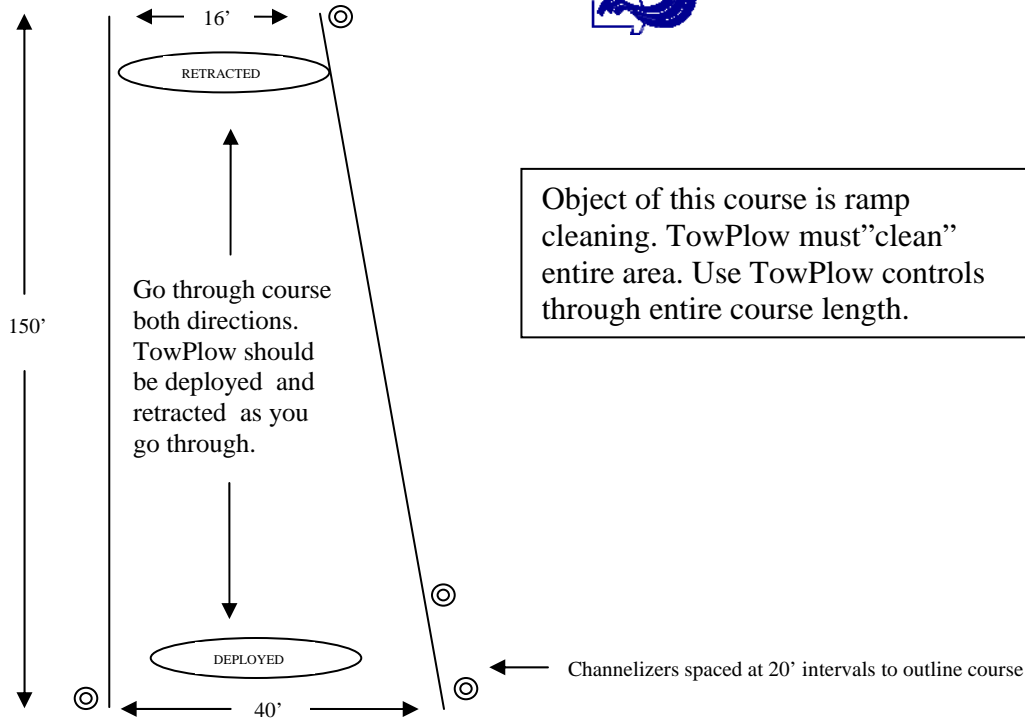
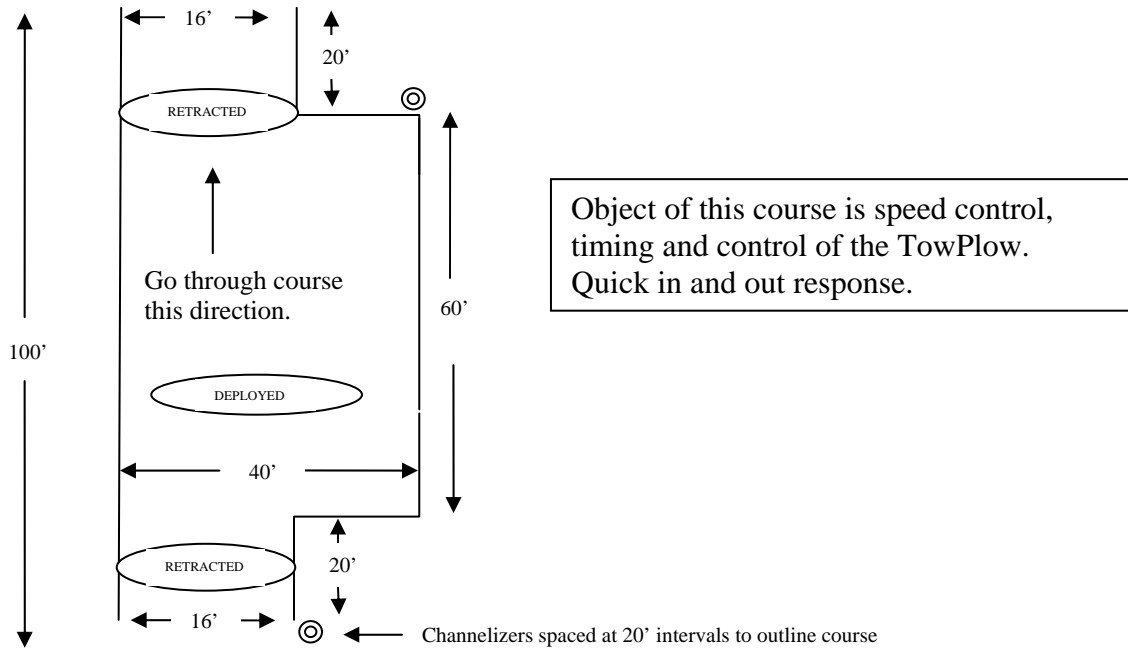




### The "Ramp"



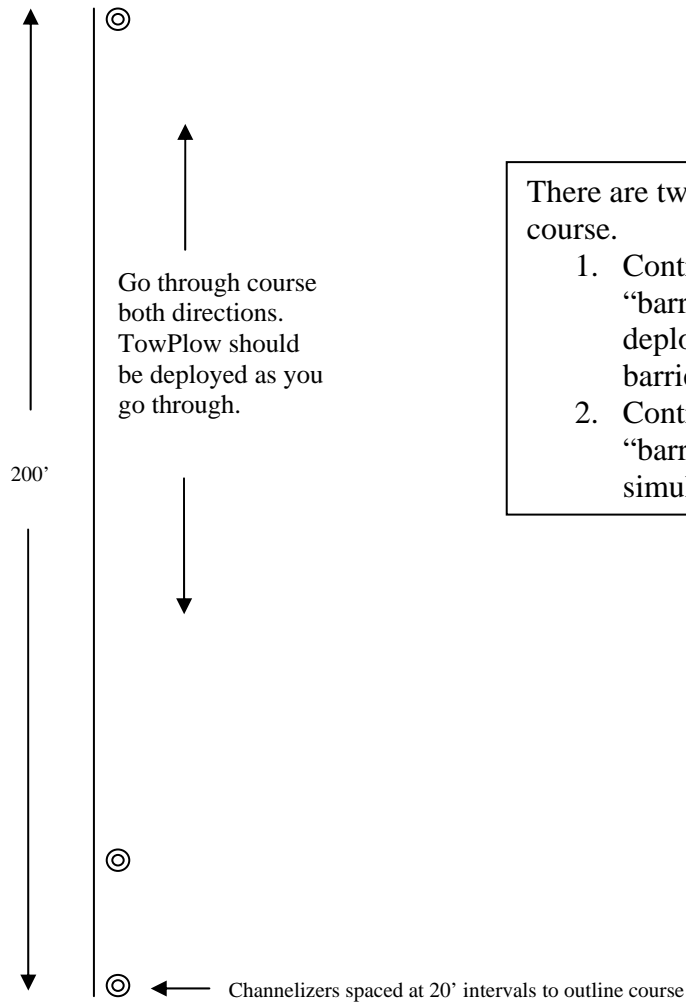
### The "Quick Change"



# Missouri Department of Transportation



## The "Barrier"

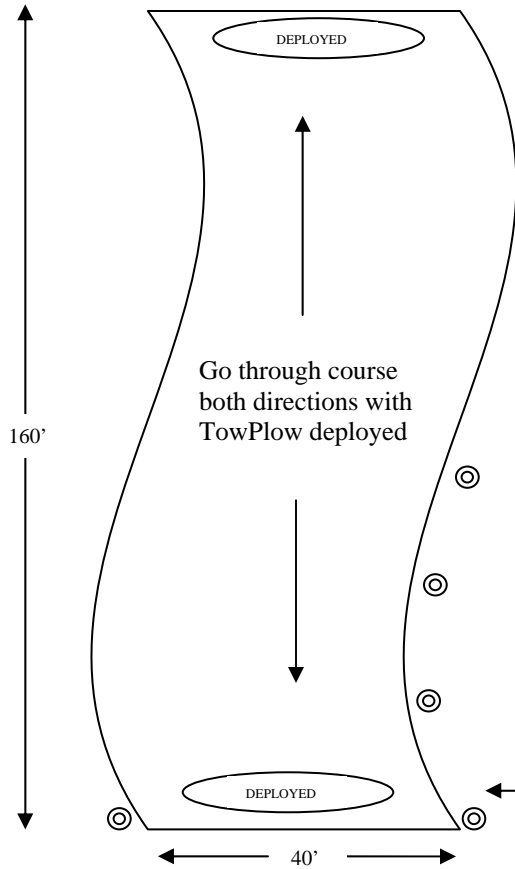


There are two objectives for this course.

1. Control front plow close to "barrier" with TowPlow deployed to simulate median barrier.
2. Control TowPlow close to "barrier" deployed to simulate guardrail.



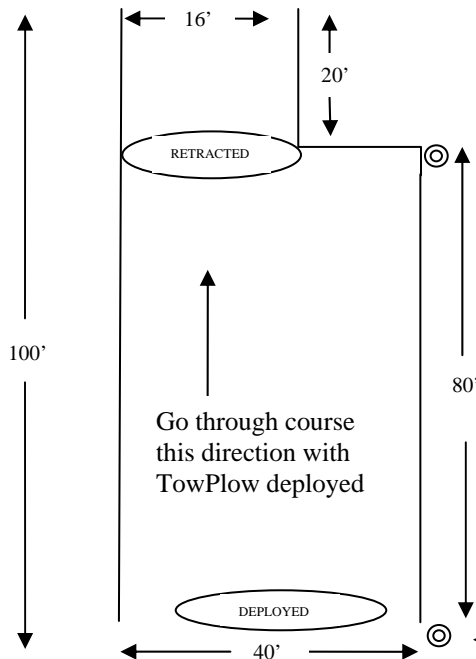
### The "S" curve



Object of this course is steering control and perception of distance. Mirror usage is critical.

Channelizers spaced at 20' intervals to outline course. Move cones over 5' at the 20' spacing to construct the "S".

### The "Parked Car"



Object of this course is speed control, recognizing obstacle in the way, timing and control of the TowPlow.

Channelizers spaced at 20' intervals to outline course