**The “Ramp”**

Go through course both directions. TowPlow should be deployed and retracted as you go through.

Object of this course is ramp cleaning. TowPlow must “clean” entire area. Use TowPlow controls through entire course length.

**The “Quick Change”**

Go through course this direction.

Object of this course is speed control, timing and control of the TowPlow. Quick in and out response.

Channelizers spaced at 20’ intervals to outline course.
The “Barrier”

Go through course both directions. TowPlow should be deployed as you go through.

There are two objectives for this course.

1. Control front plow close to “barrier” with TowPlow deployed to simulate median barrier.
2. Control TowPlow close to “barrier” deployed to simulate guardrail.

200’

Channelizers spaced at 20’ intervals to outline course
The “S” curve

Go through course both directions with TowPlow deployed

Channelizers spaced at 20’ intervals to outline course. Move cones over 5’ at the 20’ spacing to construct the “S”.

Object of this course is steering control and perception of distance. Mirror usage is critical.

The “Parked Car”

Go through course this direction with TowPlow deployed

Channelizers spaced at 20’ intervals to outline course

Object of this course is speed control, recognizing obstacle in the way, timing and control of the TowPlow.